Message Progression in Parallel Computing -To Thread or not to Thread?

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Non-blocking Interfaces

- can help to hide latency
- mitigate effects of process skew
- reported application speedup up to 1.9
- requires much effort at the algorithm and implementation levels

Examples

- MPI offers non-blocking point-to-point
- non-blocking collectives are discussed for MPI-3
- GASNet is fully non-blocking
- Asynchronous I/O

Non-blocking does not mean asynchronous!



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Non-blocking Send/Receive

- eager protocol/copy for small messages
 - \rightarrow uses a single message
- rendezvous protocol/synchronize for large messages
 → uses multiple messages (two to three)
- OS bypass networking
 - \rightarrow does not involve the kernel in send/receive
 - \rightarrow polling to check for messages

Non-blocking Collectives

- similar issues as send/receive
- much more complex tasks and protocols
- multiple send/receive operations and dependencies in a single collective operation

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Progression Strategies I/II

Manual Progression

- simplest to implement in a middleware
- user has to progress (e.g., calling MPI_Test)
- number of necessary progress calls depends on protocol
- best case: eager, worst case: pipelined protocols
- our proposed black-box scheme: $N = \lfloor \frac{size}{interval} \rfloor + 1$



Hardware-based Progression

- need to run full protocol in NIC
- complicated to implement
- full benefits to the user
- mostly not supported

Threaded Progression

- asynchronous threads
- often stated as "silver bullet" but not widely used (?)
- problem with manual progresssion: "fire at the right time"

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- threads could solve this problem (woken up correctly)
- could enable fully asynchronous progression
- OS influence (scheduler) is significant

Threading Configurations

Spare Core vs. Fully Subscribed

- two extreme scenarios
- spare core: min P/2 cores are idle (one per process)
 → used in I/O or memory-bound applications
- fully subscribed: no cores idle
 - \rightarrow used in compute-bound applications



To Thread or not to Thread?

Implementation Possibilities

Polling vs. Interrupt vs. Real Time



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Non-blocking Collectives and InfiniBand

Issues with Non-blocking Collectives

- NBCs introduce dependencies
 - \rightarrow e.g., sending a message in a tree
- dependencies might lead to synchronization

Case-study InfiniBand

- supports polling and interrupt
- polling bad without non-spare core, else fastest
- interrupts are slow and cause overhead
- scheduler issues! (timeslice 4ms, latency 3μs)

Real-Time Threads in Linux

- highest priority
- scheduled immediately
- no preemption

Overhead of Threading

Real time vs. Normal

- normal threads: interrupts coalesc, low (no) progression
- RT-threads: each interrupt pays full overhead



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Point-to-point overhead



NBC_lallreduce Overhead on 32 Nodes - spare core



NBC_lallreduce Overhead on 32 Nodes - fully subscribed



Nice Results ... but wrong Metric

Wrong Metric?

- often used time-based benchmark
- hides interrupt overhead costs!
- overhead \approx 3.4 μ s per interrupt
- many many interrupts in an NBC; 1016 in pipelined case

Work-based benchmark

- compute fixed work quantum
- results account for interrupt overhead
- should be used for any threaded progression analysis!

Work-based results - fully subscribed - not so nice



Summary and Future Work

Summary

- we developed fully threaded LibNBC for IB
 → high overhead
- tested implementation with RT threads
 - \rightarrow lower overhead (better than theory?)
- implemented new work-based benchmarking metric
 → realistic (high) overhead

Conclusions and Future Work

- threaded implementation makes sense with spare cores
- very tricky without spare cores → manual again?
- investigate other options
 - ightarrow signalled progression (not safe/realistic!)
 - ightarrow OS involvement (opposite to OS bypass)
 - \rightarrow hardware progression

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